

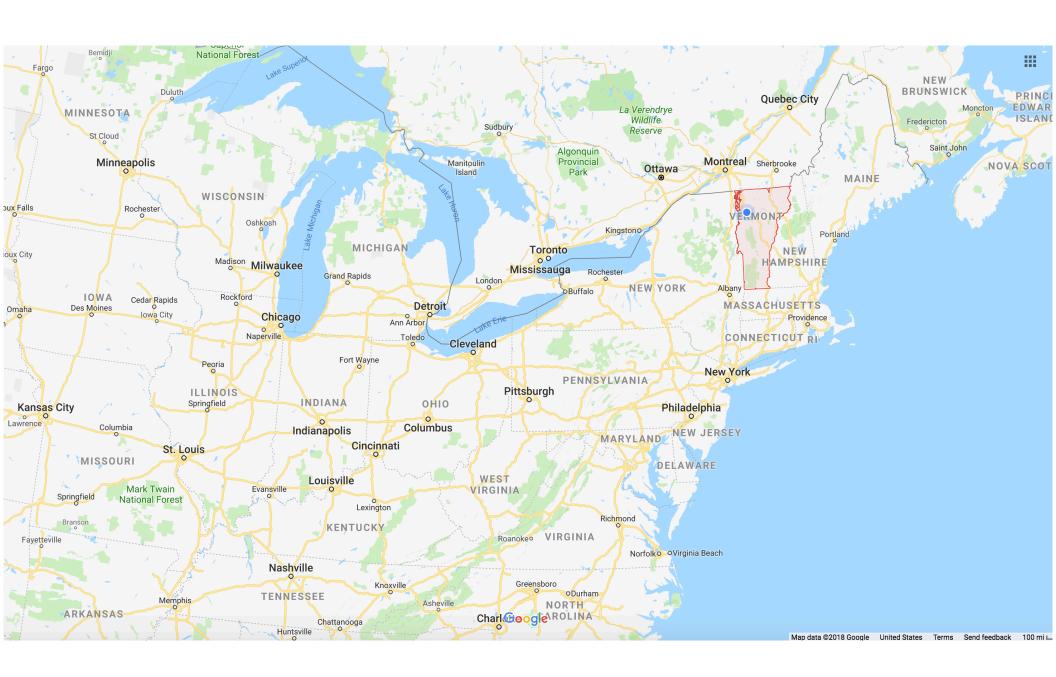
Using

evolutionary robotics

to study

embodied cognition.

Josh Bongard University of Vermont



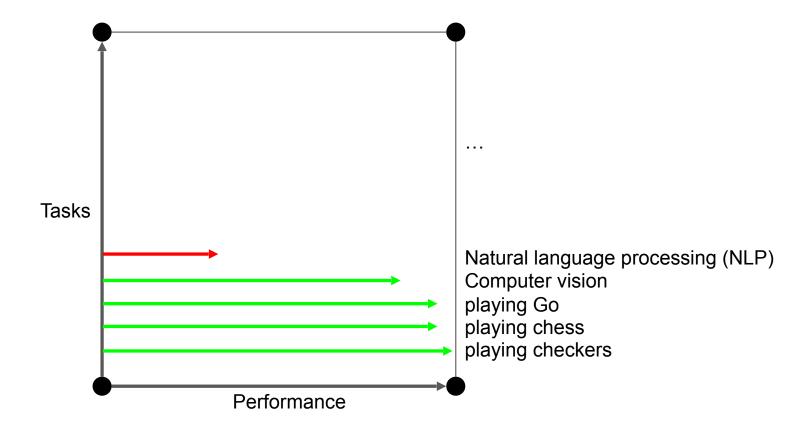


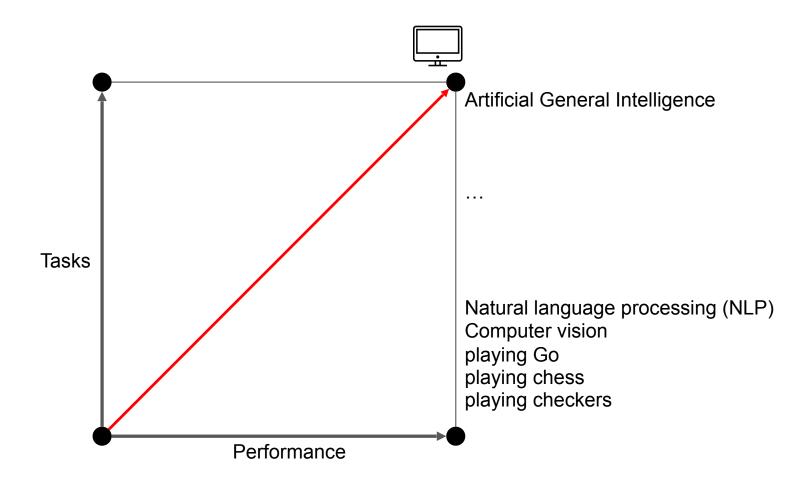
UVM Complex Systems Center @uvmcomplexity · 17h

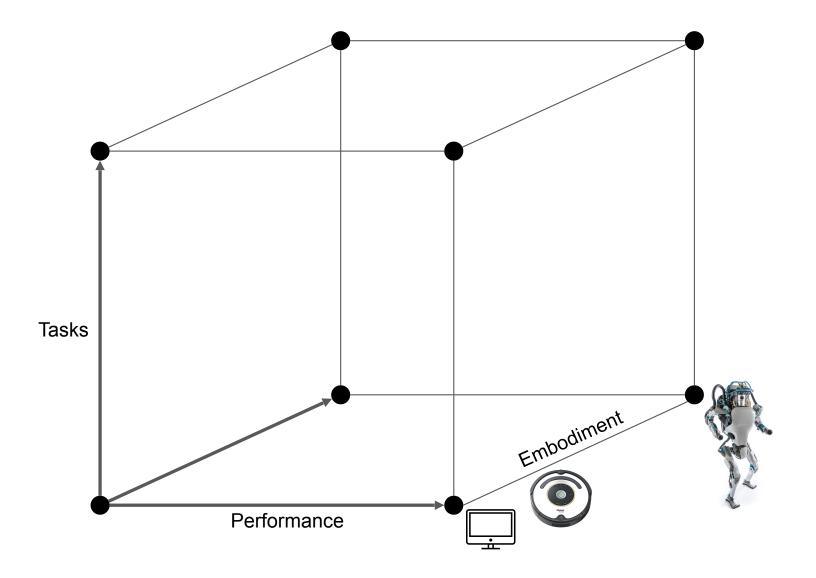
The **Vermont Complex** Systems Center has 7 Ph.D./Master's fellowships open in **Complex** Systems and Data Science. Applications are now open for Fall 2019. Help us spread the word! Learn more here bit.ly/complex-fellow...

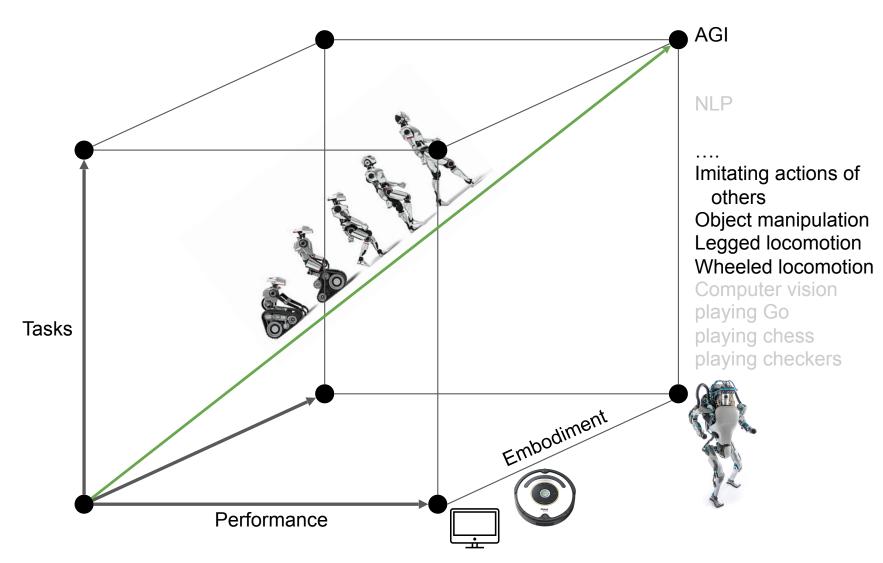




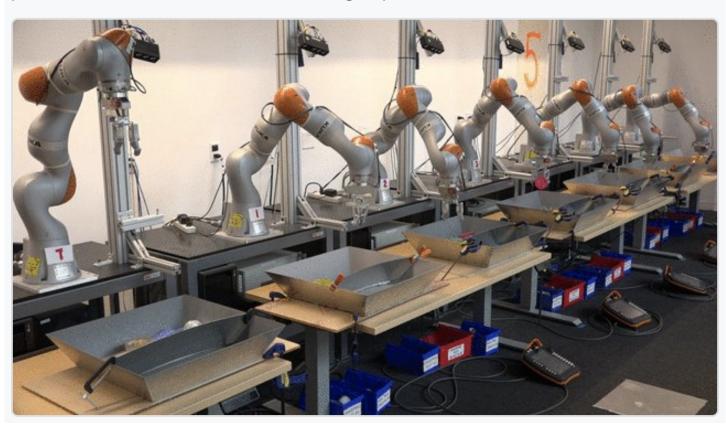


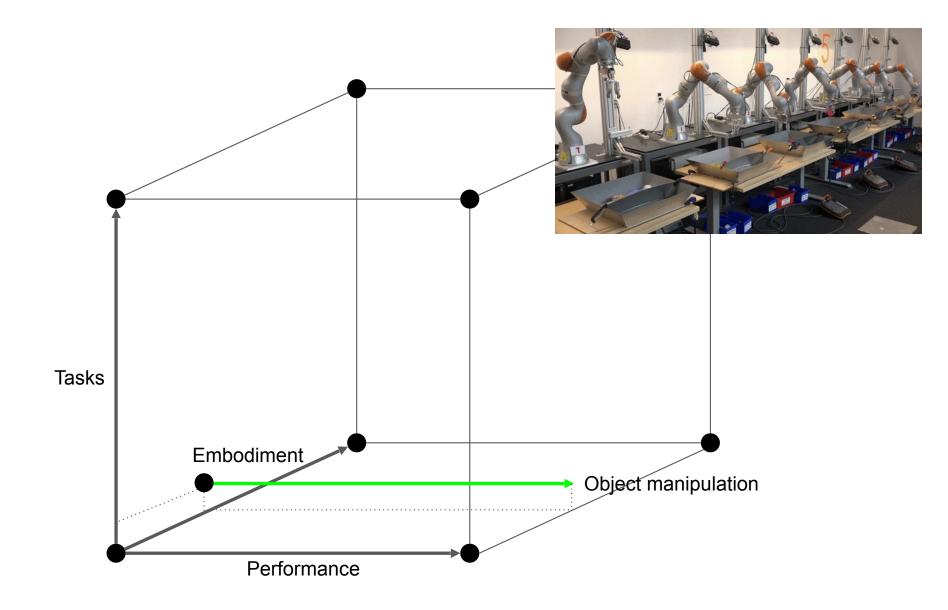


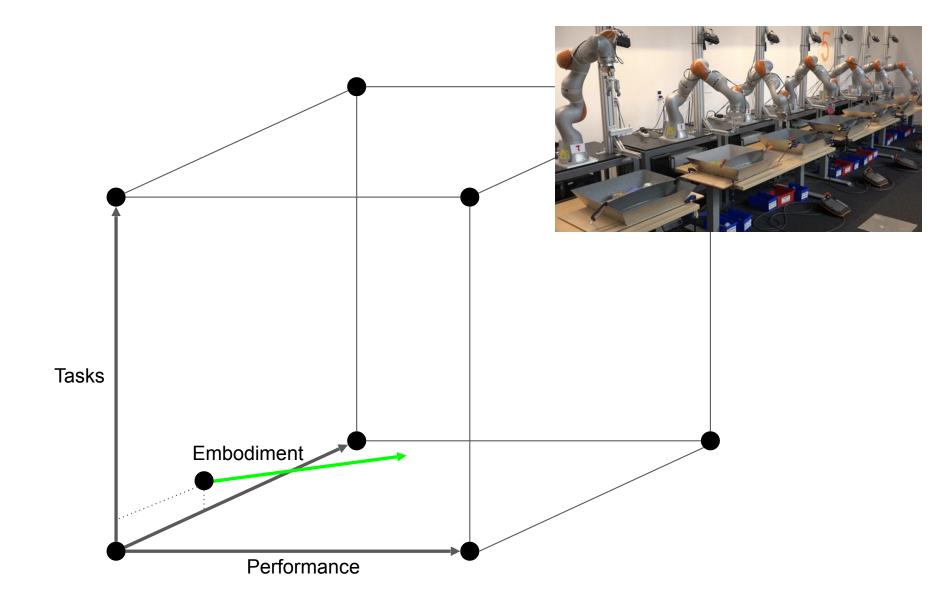


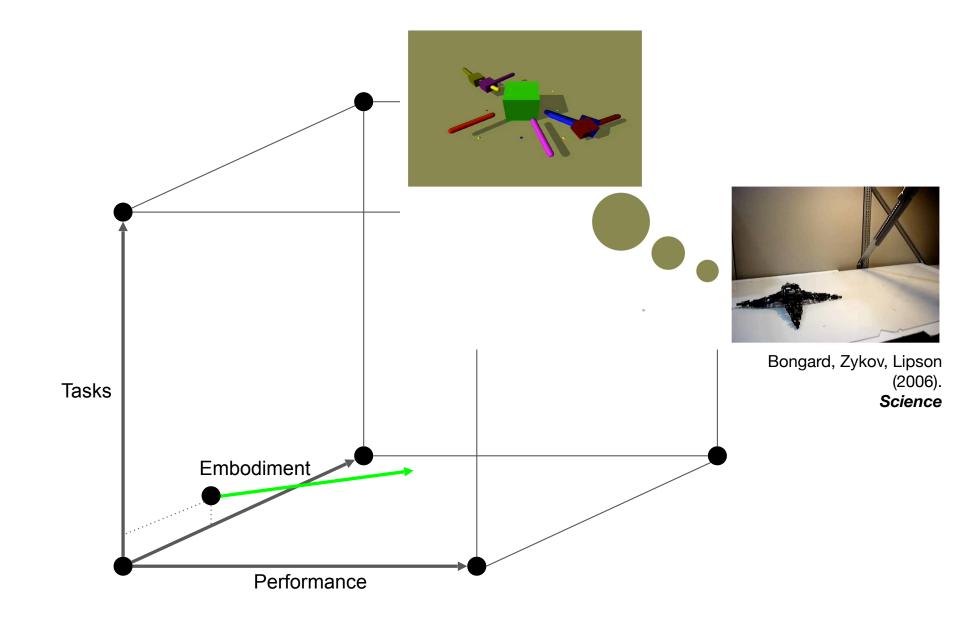


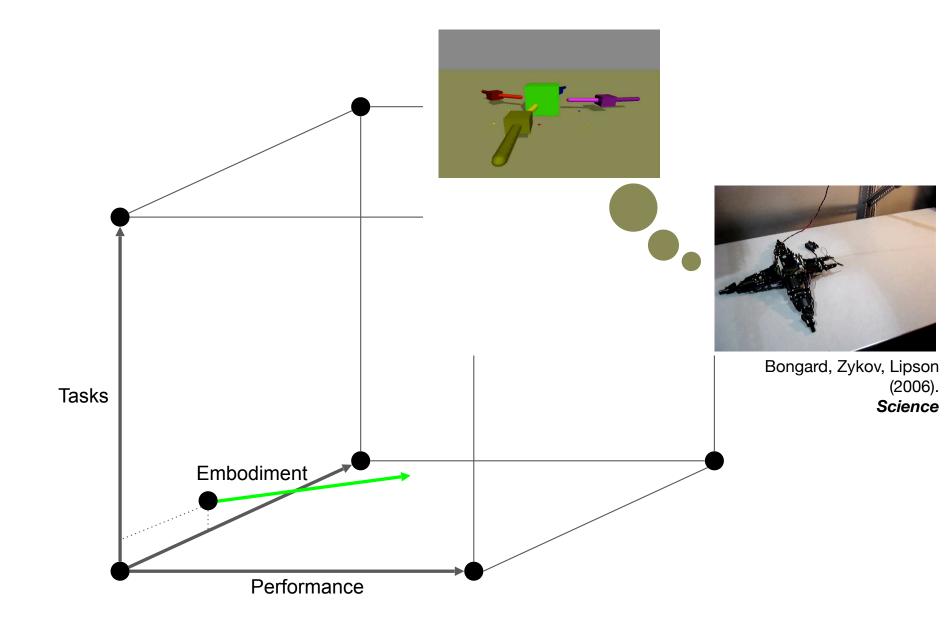
Scalable Deep Reinforcement Learning for Robotic Manipulation ai.googleblog.com/2018/06/scalab... hand-designed init -> 580k grasp attempts on 7 **robot** arms over 4 months (raw monocular RGB camera input) -> 1.2M param net -> **96**% successful test set grasps

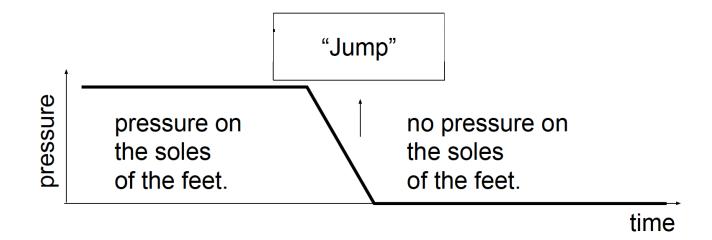


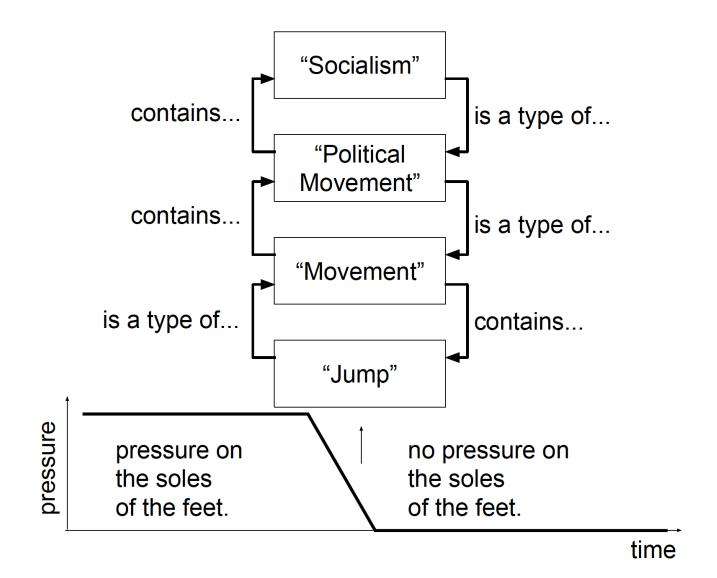


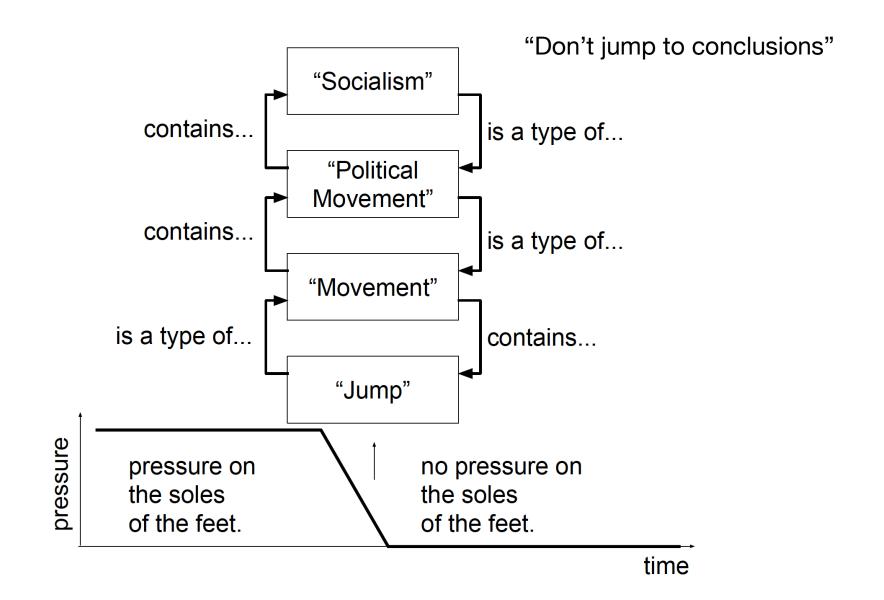




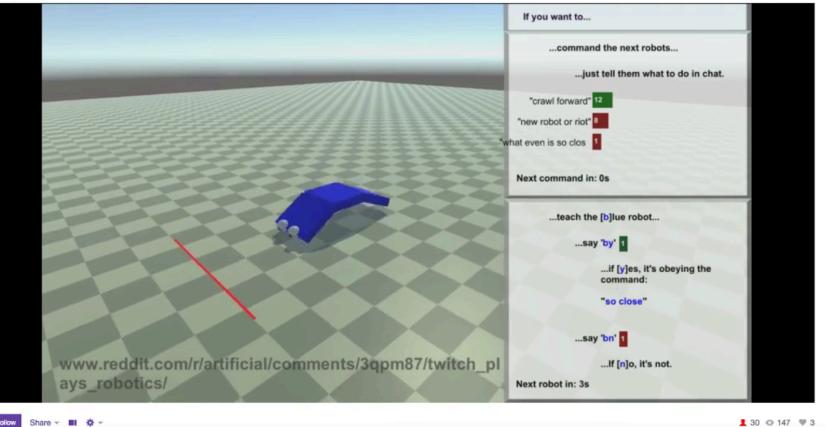








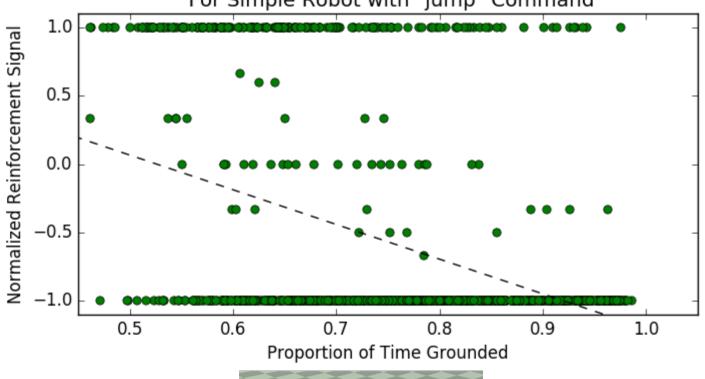


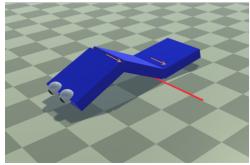


2:12 TCGMYT: hey, does it count multiple times? 2:12 kssummer: crawl forward 2:12 TCGMYT: crawl forward 2:12 IcelceChafey: Crawl forward 2:12 ArmyOfAnarchists: new robot or riot 2:12 Kinrany: moonwalk 2:12 ApatheticWrath: pitchforks ready ------2:13 Rinsmaster: crawl forward 2:13 jojo_321: crawl forward 2:13 kssummer; bn 2:13 ArmyOfAnarchists: new robot or riot 2:13 kssummer: crawl forward 2:13 ArmyOfAnarchists: new robot or riot 2:13 ArmyOfAnarchists: new robot or riot 2:13 ArmyOfAnarchists: (2) 2:13 kssummer: bn 2:13 TCGMYT: crawl forward 2:13 Lukelink1: crawl forward 2:13 kssummer: crawl forward 2:14 ArmyOfAnarchists: vy 2:14 ArmyOfAnarchists: by 2:14 kssummer: bn 2:14 kssummer: crawl forward 2:14 TCGMYT: crawl forward Send a message

janetsbe

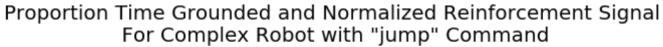
Proportion Time Grounded and Normalized Reinforcement Signal For Simple Robot with "jump" Command

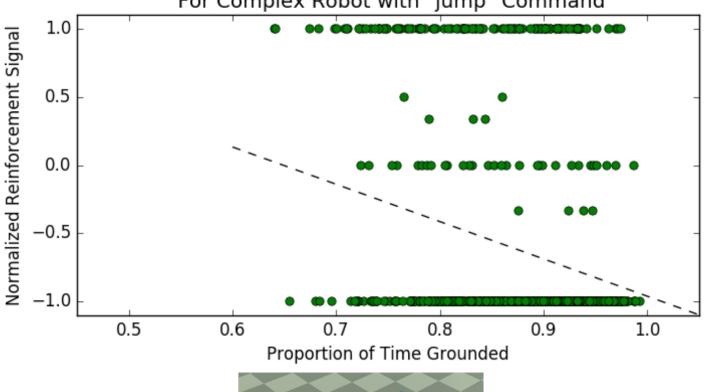


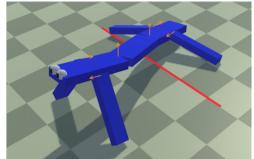


Anetsberger & Bongard (2016). Procs of ALife.

twitch.tv/twitchplaysrobotics





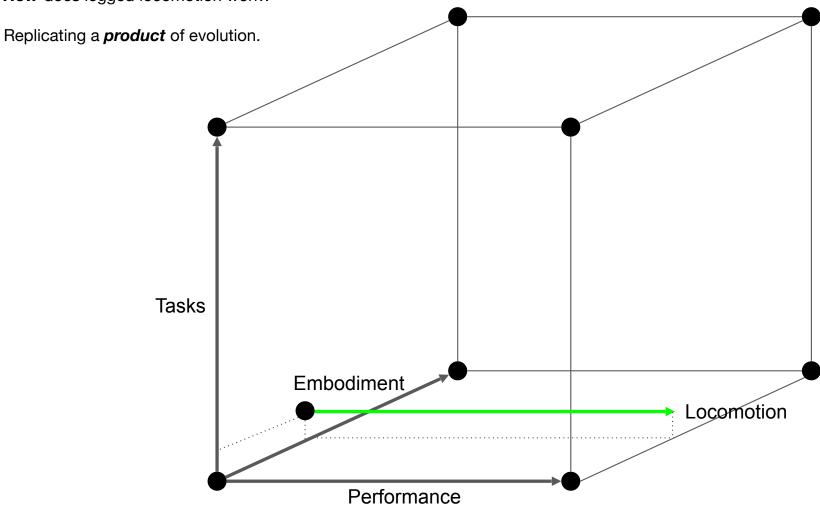


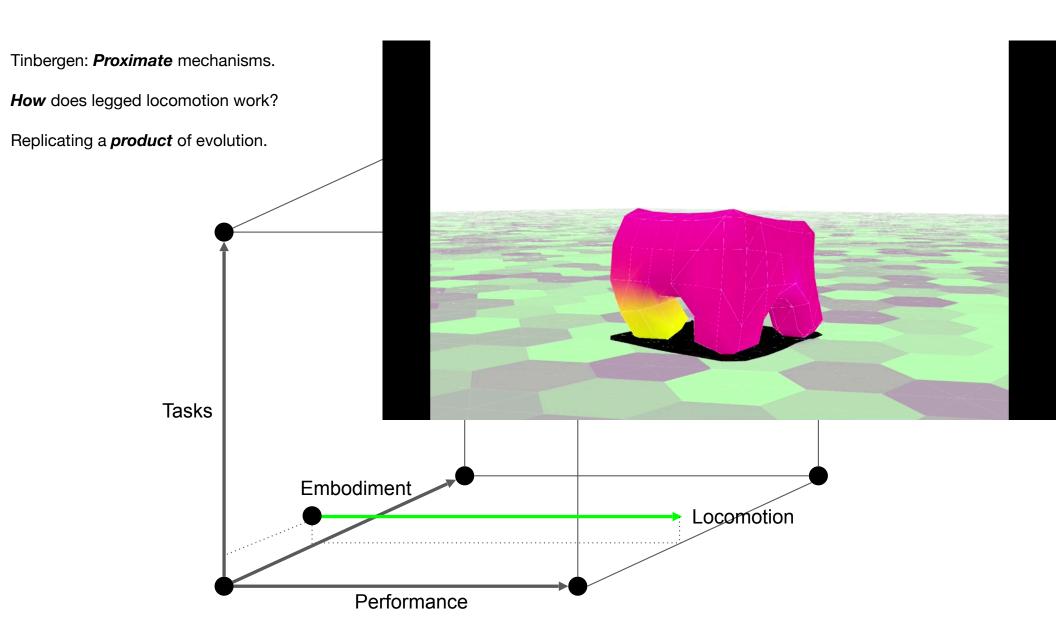
Anetsberger & Bongard (2016). Procs of ALife.

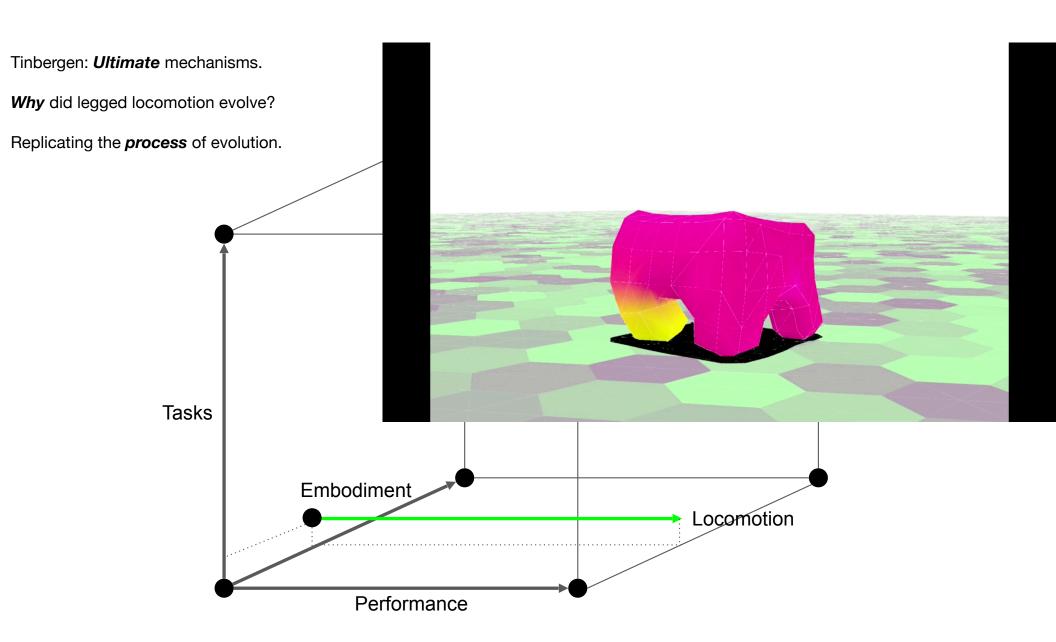
twitch.tv/twitchplaysrobotics

Tinbergen: **Proximate** mechanisms.

How does legged locomotion work?







Tinbergen: *Ultimate* mechanisms.

Why did legged locomotion evolve? Replicating the *process* of evolution. Tasks Embodiment Performance